

# CS 188: Artificial Intelligence Spring 2010

## Lecture 23: Perceptrons 4/15/2010

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Many slides adapted from Dan Klein.

## Announcements

- Project 4: due tonight.
- W7: out tonight.
- Final Contest: up and running!

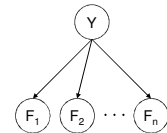
## Outline

- Naïve Bayes recap
- Smoothing
- Generative vs. Discriminative
- Perceptron

## Recap: General Naïve Bayes

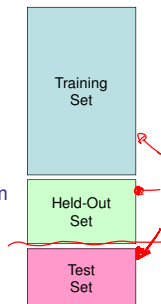
- A general *naïve Bayes* model:
  - Y: label to be predicted
  - $F_1, \dots, F_n$ : features of each instance

$$P(Y, F_1 \dots F_n) = P(Y) \prod_i P(F_i | Y)$$



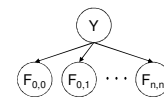
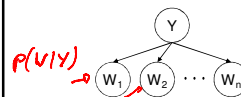
## Naïve Bayes Training

- Data: labeled instances, e.g. emails marked as spam/ham by a person
  - Divide into training, held-out, and test
- Features are known for every training, held-out and test instance
- Estimation: count feature values in the training set and normalize to get maximum likelihood estimates of probabilities
- Smoothing (aka regularization): adjust estimates to account for unseen data



## Example Naïve Bayes Models

- Bag-of-words for text
  - One feature for every word position in the document
  - All features **share** the same conditional distributions
  - Maximum likelihood estimates: word frequencies, by label
- Pixels for images
  - One feature for every pixel, indicating whether it is on (black)
  - Each pixel has a **different** conditional distribution
  - Maximum likelihood estimates: how often a pixel is on, by label



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## Recap: Laplace Smoothing

- Laplace's estimate (extended):

- Pretend you saw every outcome  $k$  extra times

$$P_{LAP,k}(x) = \frac{c(x) + k}{c(\cdot) + k|X|}$$

- What's Laplace with  $k = 0$ ?
- $k$  is the strength of the prior



$$P_{LAP,0}(X) = \left\langle \frac{2}{3}, \frac{1}{3} \right\rangle$$

$$P_{LAP,1}(X) = \left\langle \frac{3}{5}, \frac{2}{5} \right\rangle$$

- Laplace for conditionals:

- Smooth each condition:
- Can be derived by dividing

$$P_{LAP,100}(X) = \left\langle \frac{102}{203}, \frac{101}{203} \right\rangle$$

$$P_{LAP,k}(x|y) = \frac{c(x, y) + k}{c(\cdot, y) + k|X|}$$

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## Better: Linear Interpolation

- Linear interpolation for conditional likelihoods

- Idea:** the conditional probability of a feature  $x$  given a label  $y$  should be close to the marginal probability of  $x$

- Example:** A rare word like "interpolation" should be similarly rare in both ham and spam (a priori)

- Procedure:** Collect relative frequency estimates of both conditional and marginal, then average

$$P_{ML}(x|y) = \frac{\text{count}(x, y)}{\text{count}(\cdot, y)} \quad P_{ML}(x) = \frac{\text{count}(x)}{\text{count}(\cdot)}$$

$$P_{LIN}(x|y) = (1 - \alpha)P_{ML}(x|y) + \alpha P_{ML}(x)$$

- Effect:** Features have odds ratios closer to 1

## Real NB: Smoothing

- Odds ratios without smoothing:

$$\frac{P(W|\text{ham})}{P(W|\text{spam})}$$

south-west	: inf
nation	: inf
morally	: inf
nicely	: inf
extent	: inf
...	

$$\frac{P(W|\text{spam})}{P(W|\text{ham})}$$

screens	: inf
minute	: inf
guaranteed	: inf
\$205.00	: inf
delivery	: inf
...	

## Real NB: Smoothing

- Odds ratios after smoothing:

$$\frac{P(W|\text{ham})}{P(W|\text{spam})}$$

helvetica	: 11.4
seems	: 10.8
group	: 10.2
ago	: 8.4
areas	: 8.3
...	

$$\frac{P(W|\text{spam})}{P(W|\text{ham})}$$

verdana	: 28.8
Credit	: 28.4
ORDER	: 27.2
<FONT>	: 26.9
money	: 26.5
...	

Do these make more sense?

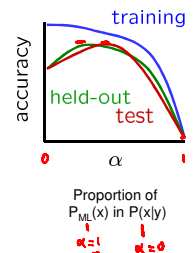
## Tuning on Held-Out Data

- Now we've got two kinds of unknowns

- Parameters:  $P(F_i|Y)$  and  $P(Y)$
- Hyperparameters, like the amount of smoothing to do:  $k, \alpha$

- Where to learn which unknowns

- Learn parameters from training set
- Can't tune hyperparameters on training data (why?)
- For each possible value of the hyperparameters, train and test on the held-out data
- Choose the best value and do a final test on the test data



## Baselines

- First task when classifying: get a **baseline**
  - Baselines are very simple "straw man" procedures
  - Help determine how hard the task is
  - Help know what a "good" accuracy is
- Weak baseline: most frequent label classifier**
  - Gives all test instances whatever label was most common in the training set
  - E.g. for spam filtering, might label everything as spam
  - Accuracy might be very high if the problem is skewed
- When conducting real research, we usually use previous work as a **(strong) baseline**

## Confidences from a Classifier

- The confidence of a classifier:
    - Posterior of the most likely label
      - $confidence(x) = \max_y P(y|x)$
    - Represents how sure the classifier is of the classification
    - Any probabilistic model will have confidences
    - No guarantee confidence is correct
  - Calibration
    - Strong calibration: confidence predicts accuracy rate
    - Weak calibration: higher confidences mean higher accuracy
    - What's the value of calibration?
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## Naïve Bayes Summary

- Bayes rule lets us do diagnostic queries with causal probabilities
- The naïve Bayes assumption takes all features to be independent given the class label
- We can build classifiers out of a naïve Bayes model using training data
- Smoothing estimates is important in real systems
- Confidences are useful when the classifier is calibrated

## What to Do About Errors

- Problem: there's still spam in your inbox
  - Need more features – words aren't enough!
    - Have you emailed the sender before?
    - Have 1K other people just gotten the same email?
    - Is the sending information consistent?
    - Is the email in ALL CAPS?
    - Do inline URLs point where they say they point?
    - Does the email address you by (your) name?
- Naïve Bayes models can incorporate a variety of features, but tend to do best in homogeneous cases (e.g. all features are word occurrences)

## Outline

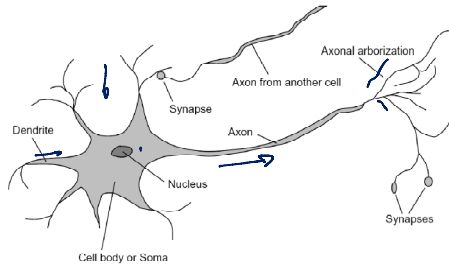
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## Generative vs. Discriminative

- Generative classifiers:
    - E.g. naïve Bayes
    - A causal model with evidence variables
    - Query model for causes given evidence
  - Discriminative classifiers:
    - No causal model, no Bayes rule, often no probabilities at all!
    - Try to predict the label Y directly from X
    - Robust, accurate with varied features
    - Loosely: mistake driven rather than model driven
- Handwritten notes:  $\theta = \{P(y), P(x_i|y)\}$ , likelihood:  $\prod_{i=1}^n P(x_i|y)$ ,  $\theta = \text{argmax } L(\theta)$ , later: use  $\theta(y|x)$ , find  $\theta$  s.t. accuracy of prediction using  $\theta(y|x)$  is maximal training data.

## Some (Simplified) Biology

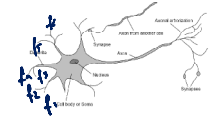
- Very loose inspiration: human neurons



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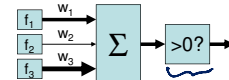
## Linear Classifiers

- Inputs are **feature values**
- Each feature has a **weight**
- Sum is the **activation**



$$\text{activation}_w(x) = \sum_i w_i \cdot f_i(x) = \underline{w \cdot f(x)}$$

- If the activation is:
  - Positive, output +1
  - Negative, output -1



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## Example: Spam

- Imagine 4 features (spam is "positive" class):

- free (number of occurrences of "free")  $w \cdot f(x)$
- money (occurrences of "money")
- BIAS (intercept, always has value 1)

$x$   
"free money"

BIAS	: 1
free	: 1
money	: 1
...	

BIAS	: -3
free	: 4
money	: 2
...	

$$\sum_i w_i \cdot f_i(x)$$

$$\begin{aligned} (1)(-3) &+ \\ (1)(4) &+ \\ (1)(2) &+ \\ \dots & \\ &= 3 \end{aligned}$$

## Binary Decision Rule

- In the space of feature vectors
  - Examples are points
  - Any weight vector is a hyperplane
  - One side corresponds to  $Y=+1$
  - Other corresponds to  $Y=-1$

$$w \cdot f > 0$$

BIAS	: -3
free	: 4
money	: 2
...	

